

# Lecture # 23

## 2.17 STREAMLINES

A streamline is a curve drawn in the fluid such that the tangent to it at every point is in the direction of fluid velocity  $\bar{V}$  at that point at the instant considered . A streamline is also called the line of flow .

Since a streamline is everywhere parallel to the direction of flow , we may conclude that there cannot be any flow across a streamline i.e. the fluid cannot cross a streamline . Thus physically , the streamlines are viewed as being solid boundaries with the fluid flowing with them .

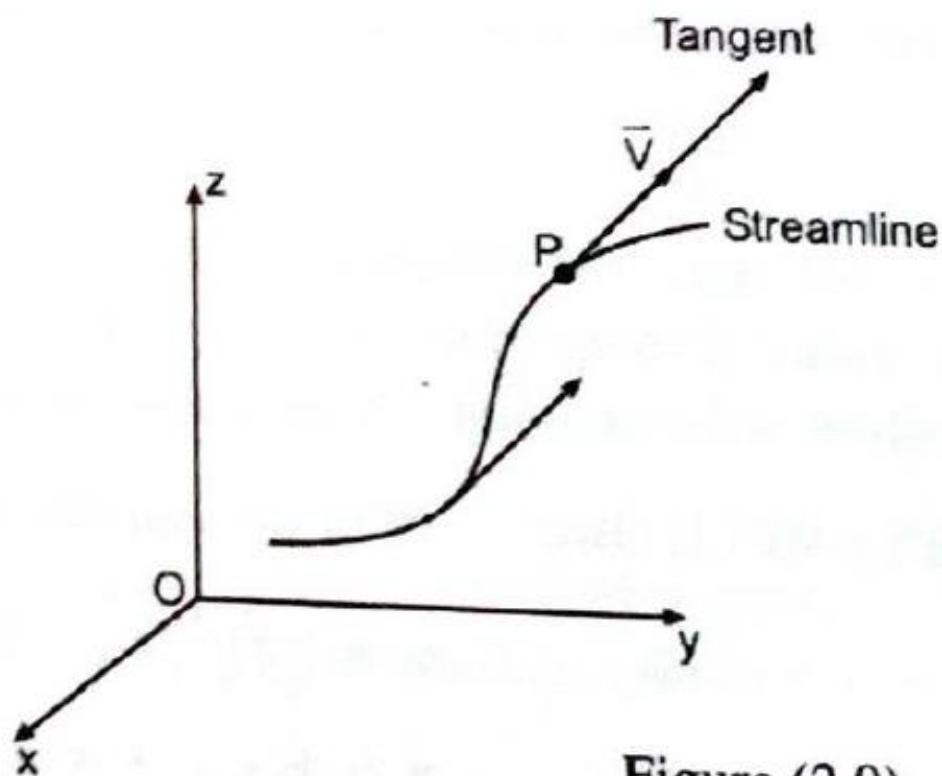


Figure (2.9)

When the motion is steady , so that the flow pattern does not change with time , the streamlines have the same shape at all instants . In other words , the streamlines are the fixed lines in the flow field at all times . However , when the motion is unsteady , the flow pattern changes with time and the streamlines will vary from instant to instant . The photographs taken at different instants will reveal a different system of streamlines . The whole set of streamlines at a given instant , thus gives the flow pattern at that instant .

**NOTE:** It should be noted that the boundaries of stationary solid surfaces are always streamlines since the fluid cannot cross solid boundaries .

## **DIFFERENTIAL EQUATION FOR THE STREAMLINES**

Since at each point of a streamline, the velocity vector  $\vec{V}$  is parallel to the unit tangent vector  $\hat{t} = \frac{d\vec{r}}{ds}$  to the streamline at that point, therefore  $\vec{V} \times \frac{d\vec{r}}{ds} = \vec{0}$  or  $\vec{V} \times d\vec{r} = \vec{0}$

i.e. 
$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ u & v & w \\ dx & dy & dz \end{vmatrix} = \vec{0}$$

or 
$$(v dz - w dy) \hat{i} + (w dx - u dz) \hat{j} + (u dy - v dx) \hat{k} = \vec{0} \quad (1)$$

or 
$$v dz - w dy = 0 \quad (2)$$

$$w dx - u dz = 0 \quad (3)$$

$$u dy - v dx = 0$$

From equations (1), (2), and (3), we get

$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w} \quad (4)$$

Equation (4) is the differential equation for the streamlines regardless whether the flow is steady or unsteady.

This equation will have a pair of differential equations , which when integrated will give two equations for the streamlines , each containing a constant of integration . The streamlines are the curves of intersection of these two equations thus obtained . Thus equation (4) has a doubly infinite set of solutions corresponding to different values of the constants . The particular values of these constants serve to identify a streamline .

For two dimensional flow , the differential equation (4) reduces to

$$\frac{dx}{u} = \frac{dy}{v} \quad (5)$$

In this case , the streamlines will be obtained by integrating equation (5) . Since there will be only one constant of integration , we will have an infinite number of different streamlines corresponding to different values of the constant . A particular value of the constant serves to identify the streamline .

**EXAMPLE (10):** Find the equations of streamlines for the following flow fields :

(i)  $u = \frac{kx}{x^2 + y^2}, \quad v = \frac{ky}{x^2 + y^2}$

(ii)  $u = kx, \quad v = -ky \quad (k \text{ constant})$ .

**SOLUTION:** (i) Since the velocity field is steady and two-dimensional, therefore, from equation (5)

$$\frac{\frac{dx}{kx}}{x^2 + y^2} = \frac{\frac{dy}{ky}}{x^2 + y^2} \quad \text{or} \quad \frac{dx}{kx} = \frac{dy}{ky}$$

which on integration gives  $\ln y = \ln x + \ln C$  or  $y = Cx$  where  $C$  is the constant of integration. Hence, the streamlines are the straight lines radiating from the origin as shown in the figure (2.10).

(ii) Since the flow field is steady and two-dimensional, therefore, from equation (5) we have

$$\frac{dx}{kx} = \frac{dy}{-ky} \quad \text{or} \quad \frac{dx}{x} + \frac{dy}{y} = 0$$

or  $\ln x + \ln y = \ln C \quad \text{or} \quad xy = C$

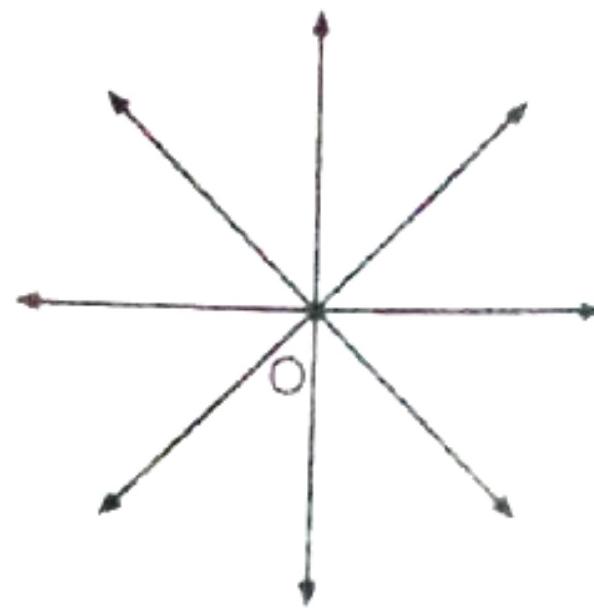


Figure (2.10)

This is the general expression for the streamlines, which are rectangular hyperbolae. The complete pattern is plotted by assigning various values to the constant  $C$ . The arrowheads can be determined only by returning back to the given velocity field to ascertain the velocity - component directions. For example, in the first quadrant ( $x > 0, y > 0$ ),  $u$  is positive and  $v$  is negative; hence the flow moves down and to the right establishing the arrow heads as shown in figure (2.11). Finally, note the peculiarity that the two streamlines ( $C = 0$ ) have opposite directions and intersect each other. This is possible only at a point where  $u = v = 0$ , which occurs at the origin in this case. Such a point of zero velocity is called a **stagnation point**.

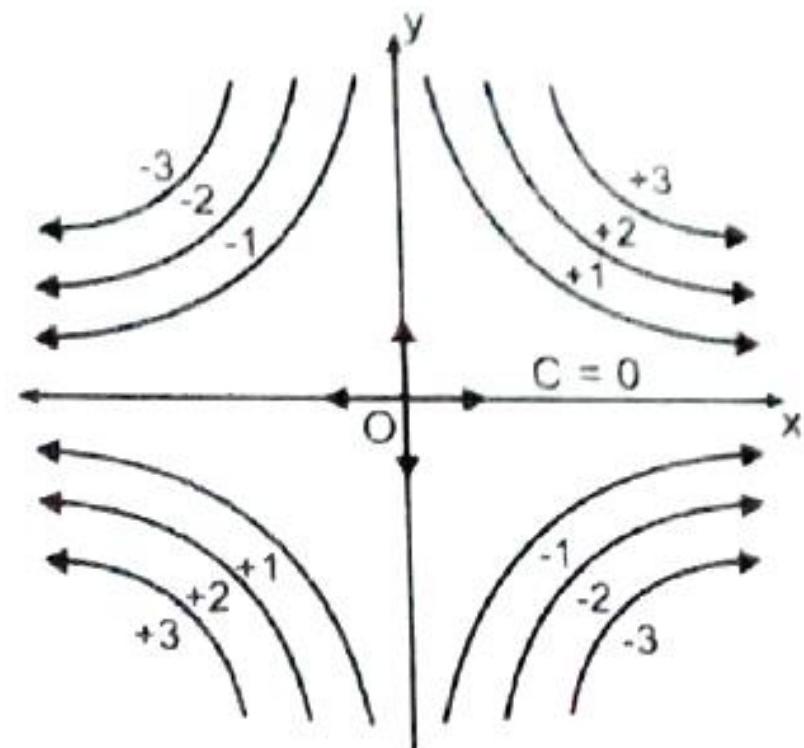


Figure (2.11)